Human behavior and social interactions in complex environments: The case study of the KTH Live-In Lab

KTH VETENSKAP OCH KONST

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Modeling Behavior in Complex Environments

Context New urban cities and residential buildings are examples of complex cyber-physical-human systems (CPHS)

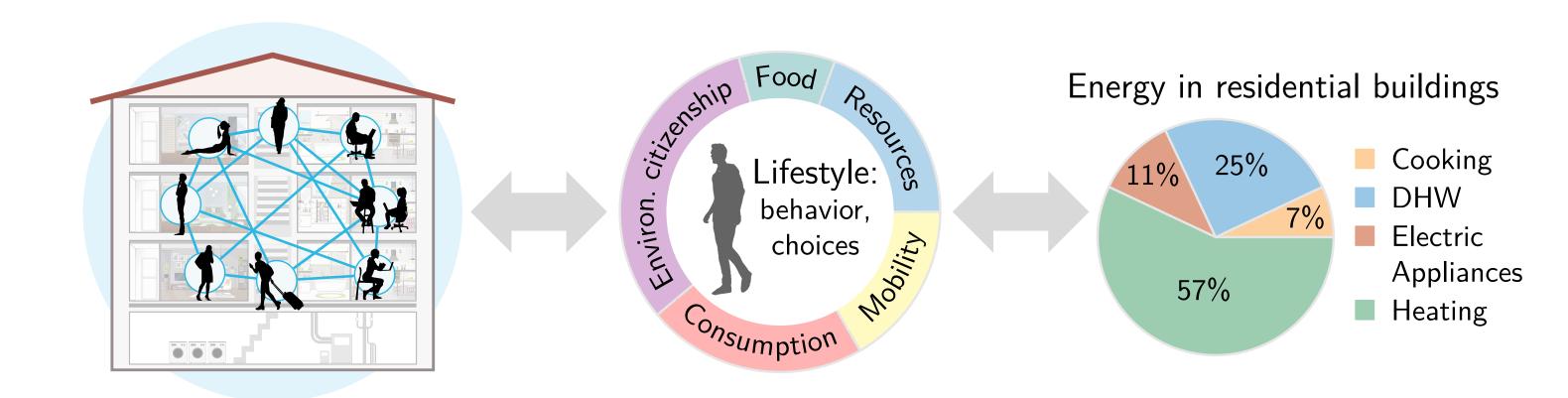
Challenges Limited comprehension of bidirectional interactions between humans and environmental conditions

Research directions

- What influences occupants' behavior pattern related to window operation in buildings?
- Can sustainable behaviors diffuse within social groups?
- How can ultimately the understanding of behavioral dynamics trigger energy efficiency?



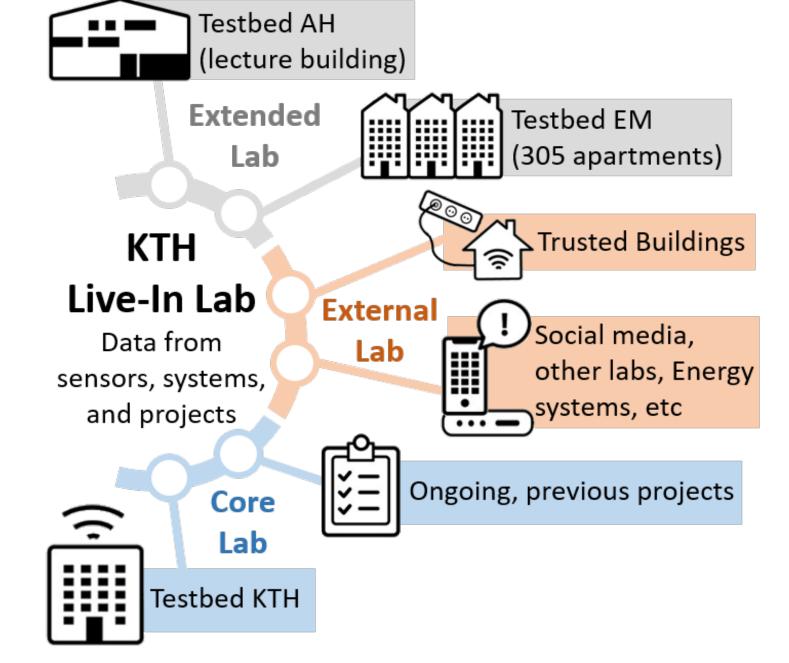
ML, data-driven control methods, social network dynamics and control, surveys and experimental campaigns,..



Example: Design of energy-efficient buildings

- Why? Buildings are estimated to account for $\approx 30\%$ -40% of overall energy use and $\approx 40\%$ of CO₂ emissions (E) IEA;Our World in Data;Itard, *OTB Rep* (2008))
- Modeling challenges include accounting for observed discrepancy between:
- 1. Predicted and measured building performance (EPG) \leftarrow occupant behavior
- 2. Surveyed and measured occupants behaviors and attitudes \leftarrow social influence

KTH Live-in-Lab: Example of CPHS Environment



State-of-the-art platform of building testbeds:

- Real-world experiments
- Collaboration platform
 & Multidisplinary research
- Flexible structure
- Multiple sensors: occupancy, ambient $(T_{\rm in}, T_{\rm out}, CO_2, RH)$, energy/water/electricity meters

CPHS environment, which combines:

(CP) KTH Live-In Lab buildings and datapool(H) KTH Live-In Lab tenants

- Ø liveinlab.kth.se/en
- Molinari M et al., Applied Energy (2023)
- Rolando D et al., *Energies* (2022)

Social Interactions and Human Behavior

Aim Show that sustainable living can be promoted through digitalization of a household into a social network of interacting tenants

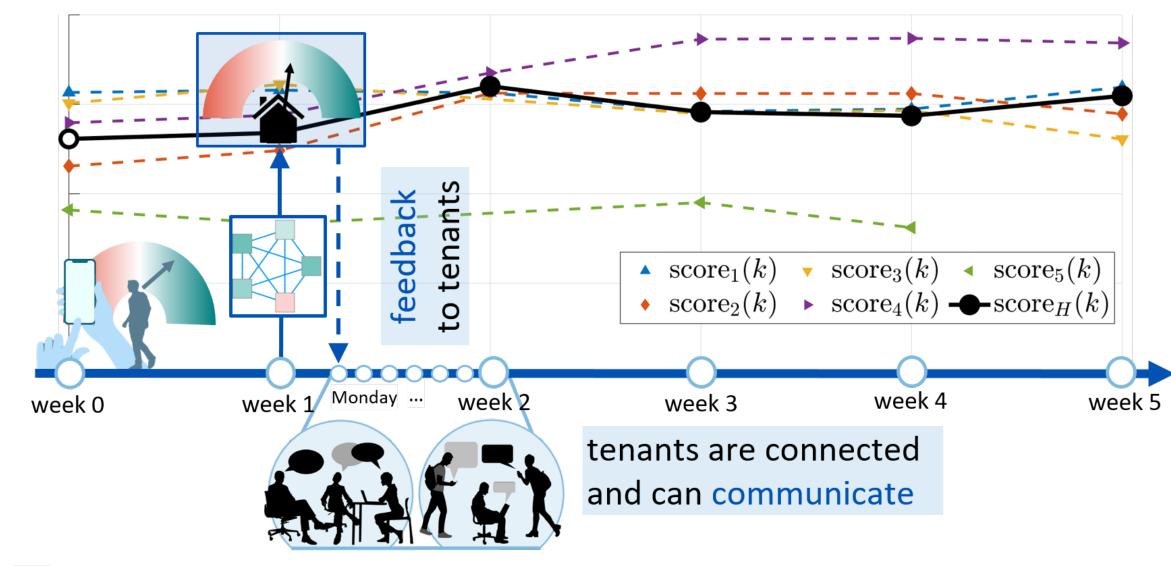
Approach Longitudinal experimental campaign, whose design is based on modeling household behaviors as a collective decision-making process

Interconnected tenants of KTH Live-In Lab as decision-makers:

Reference state from survey on habits & environmental impact of lifestyle

Weekly monitored data on sustainability practices

 \Rightarrow Sustainability scores for each tenant and for the household



End of experimental campaign: Feedback from tenants

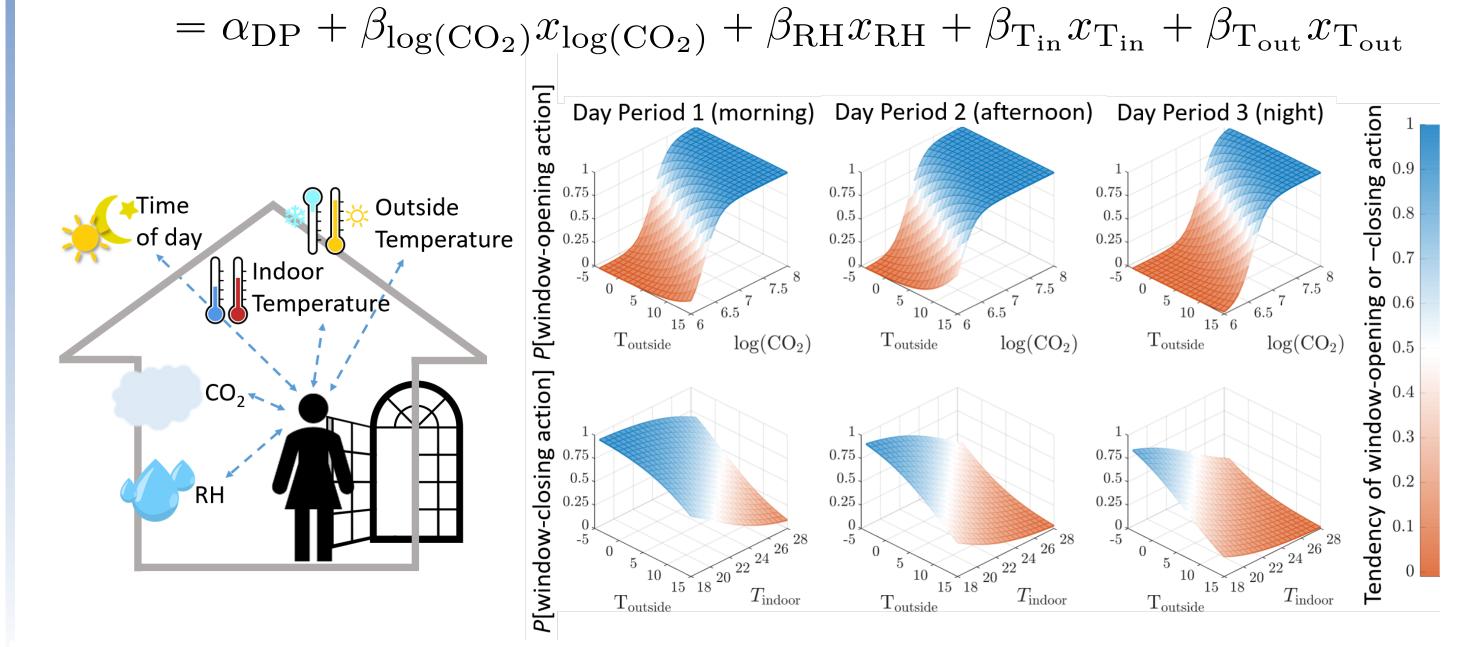
Environmental Drivers and Human Interaction

Aim Analyze physical environmental and categorical variables

Approach Selection of best fitting window-opening (window-closing) model, based on monitored data at KTH Live-In Lab (Oct-Dec 2020):

- Partition of window-opening (-closing) data: 20% (validation) 80% (training)
- Selection of significant drivers: AIC (forward/backwards) with 10-fold CV
- Computation of best model (w. training data): Logistic Regression with selected drivers
- Model validation (w. validation data): Goodness of fit

logit(P[opening/closing-window action])



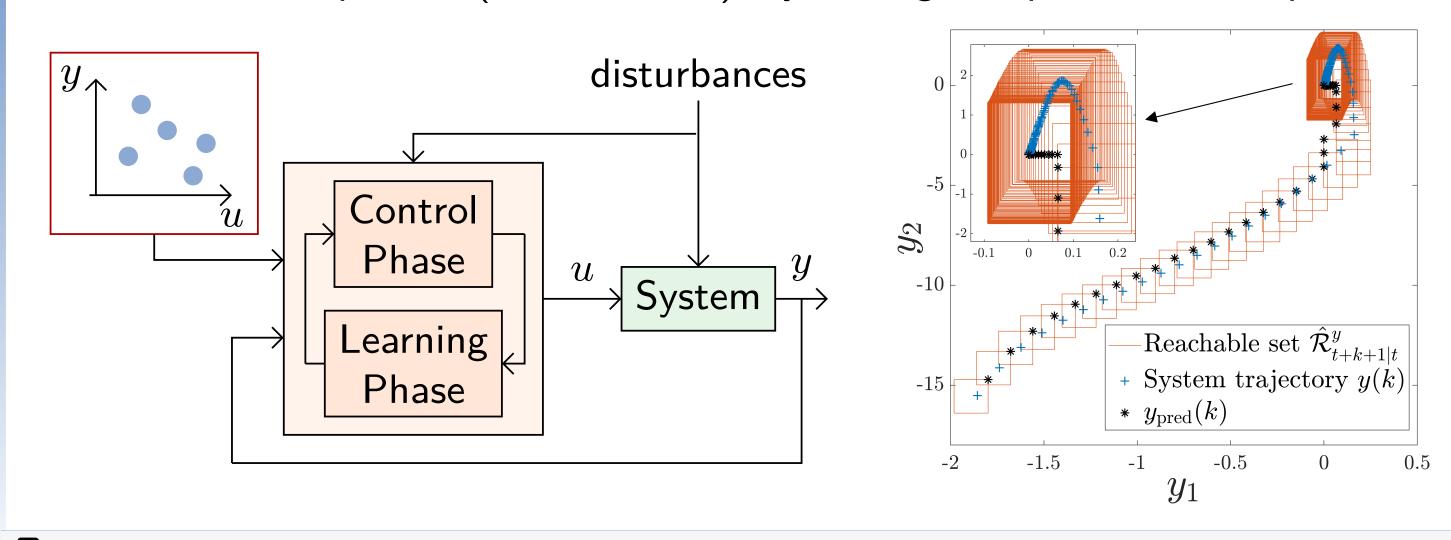
digital futures

Improve Control Strategies in Smart Buildings

Aim Develop a cost-effective control strategy that achieves optimal performance and satisfies system constraints without relying on an accurate model of the dynamical system

Approach Robust data-driven predictive control to control unknown non-linear systems under bounded process and measurement noise

- Learning phase: Implicit data-driven representation of unknown nonlinear system using zonotopes (finite horizon) and past input-output data
- Control phase: Nonlinear zonotopic predictive control (NZPC) to predict the reachable output set (finite horizon), by solving an optimal control problem



- What influences occupants' behavior in residential buildings? An experimental study on window operation in the KTH Live-In Lab, M. Farjadnia, A. Fontan, A. Russo, K. H. Johansson, M. Molinari, submitted, 2023 CCTA
- Social interactions for a sustainable lifestyle: The design of an experimental case study, A. Fontan, M. Farjadnia, J. Llewellyn, C. Katzeff, V. Cvetkovic, M. Molinari, K. H. Johansson, 2023 IFAC
- Robust data-driven predictive control of unknown nonlinear systems using reachability analysis, M. Farjadnia, A. Alanwar, U. B. Niazi, M. Molinari, K. H. Johansson, 2023 ECC